## SAMPLE QUESTION PAPER

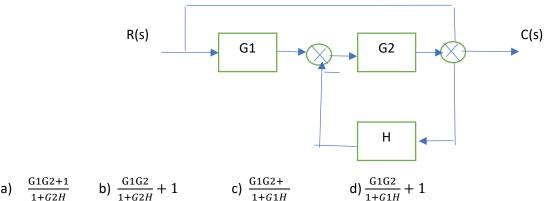
## SE (ELECTRONICS)

## R-2016

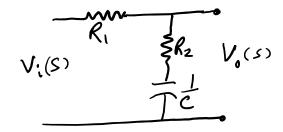
Subject: LINEAR CONTROL SYSTEM

## ALL Questions carry equal marks (02 EACH)

1. Find C(s)/R(s) for the block diagram below



- 2. In a signal flow graph, an input node is one on which
- a) Only incoming branches are connected
- b) Only outgoing branches are connected
- c) Both incoming and outgoing branches are connected
- d) All the nodes are connected.
- 3. Vo(s)/Vi(s) for the circuit below is



- $1+R_1Cs+R_2Cs$  $1+R_1Cs$
- $1+R_1Cs+R_2Cs$  $1+R_2Cs$
- $1+R_1Cs$
- 4. The zeros of G(s)=(s+5)/s(s+2) are
  - a) 0
- b) -2
- c) -5
- d) -5/2
- 5. The initial slope of Bode plot for open loop transfer function is

	a)	+20db/d	b)-20db/d	c) 40db/d	d) -40 db/d		
6.	a) b) c)	b) Only phase margin should be positive c) Both gain and phase margin should be positive					
7.	rep a) b) c)	Frequency domain, first order differential equations					
8.	a) b) c)	$\angle G(s)H(s)$ $\angle G(s)H(s)$ $\angle G(s)H(s)$	$= \pm (2q - 1)$ $= \pm (q + 1)$ $= \pm (2q + 1)$	)180 <sup>0</sup> and  0 180 <sup>0</sup> and  G )180 <sup>0</sup> and  0	table system in root locus approach is $G(s)H(s) =-1$ $(s)H(s) =1$ $G(s)H(s) =1$ $(s)H(s) =-1$		
9.	a) b) c)	Infinity , open loop pole					
10.	The	number of a)	branches of robbs 2		for G(s)H(s)=K/(s+2) <sup>3</sup> d) 4		
11.	The a) b) c) d)	e Nyquist plo 8+j0 -0.8+j0 0.8+j0 0+j8	t for G(s)H(s):	=10/s(s+1)(s+	_2) will cross the real axis axis at		
12. a)	The	velocity err b) 10			0(1+s)/s(1+2s) will be d) 0		
13.	The	velocity err	or constant fo	or G(s)H(s)=10	0(1+s)/s(1+2s) will be		
a)1		b) 10	c)5	d)	0		
14.	The steady state response of a system is that part of time response that goes to as time goes to						
	a) b) c) d)	Infinity, zero Infinity, infi Zero, infinit Zero, zero	o nity				

15.	The laplace transform of unit ramp function is					
	a) 1 b) $1/s$ c) $1/s^2$ d) $1/s^3$					
16.	In order to find stability from routh Hurwitz criteria, the number of in the first column of array, indicates a) Zeros, no. of roots with positive real part b) ones, no. of roots with positive real part c) sign changes, no. of roots with positive real part d) sign changes, no. of roots with negative real part					
17.	The range of K for for stability for characteristic equation s³+2ks²+(k+2)s+4=0 is a) K=1 b) K>2.73 c) K<2.73 d) K>10					
18.	Using the property of state transition matrix $\emptyset^{-1}(t)=$ a) $\emptyset^{-1}(-t)$ b) $\emptyset^{-1}(0)$ c) $\emptyset^{-1}(t)$ d) I					
19.	According to Kalman's test, a linear time invariant continuos system described by state equations $ [\dot{X}] = [A][X] + [B][U] $ [Y]=[C][X] Is completely controllable if the rank of matrix is equal to n a) $ [B:AB:AB^2::AB^{n-1}] $ b) $ [A:AB:AB^2::AB^{n-1}] $ c) $ [B:AB:A^2B::A^{n-1}B] $ d) $ [B:AB:A^2B::A^{n-1}B] $					
20.	Gain margin is the reciprocal of magnitude   G(jw)   at the frequency at which  a) Phase angle is -180  b) Phase angle is -120  c) Phase angle is 0  d) Phase angle has no relation.					
21.	The gain crossover frequency is one where the magnitude of open transfer function is a) 10 db b) 1db c) 0 db d) -1db					
22.	When a pole is added in the forward path of a second order system a) Band width decrease					

b) Rise time reduces

- c) Resonant peak reduces
- d) System becomes more stable
- 23. Which of the following is not time response specification
  - a) Maximum overshoot
  - b) Delay time
  - c) Rise time
  - d) Band width
- 24. If initial slope of Bode plot is +20 b/d, it indicates presence of
  - a) Zero at origin
  - b) Pole at origin
  - c) Zero at infinity
  - d) Pole at infinity
- 25. The check for , a part of real axis lies on root locus , is
  - a) If number of poles to the right of section is odd
  - b) If number of zeros to the right of section is odd
  - c) If number of poles plus zeroes to the right of section is even.
  - d) If number of poles plus zeroes to the right of section is odd