## SAMPLE QUESTION PAPER

## SE (ELECTRONICS)

## R-2012

## Subject: PRINCIPLE OF CONTROL SYSTEM

ALL Questions carry equal marks (02 EACH)

1. Find C(s)/R(s) for the block diagram below



- 2. In a signal flow graph , an input node is one on which
- a) Only incoming branches are connected
- b) Only outgoing branches are connected
- c) Both incoming and outgoing branches are connected
- d) All the nodes are connected.
- 3. Vo(s)/Vi(s) for the circuit below is



a) 
$$\frac{1+R_1+R_2}{1+R_1Cs}$$

b) 
$$\frac{1+R_1Cs+_2Cs}{2}$$

c) 
$$\frac{1+R_1CS}{1+R_1CS+R_2CS}$$

d) 
$$\frac{1+R_2Cs}{1+R_1Cs+R_2}$$

5. The initial slope of Bode plot for open loop transfer function is

- a) +20db/d b)-20db/d c) 40db/d d) -40 db/d
- 6. In order to stability of a system from Bode plot
  - a) Only Gain margin should be positive
  - b) Only phase margin should be positive
  - c) Both gain and phase margin should be positive
  - d) Neither gain nor phase margin should be positive
- 7. The analysis of control system using state space approach is carried out in \_\_\_\_\_\_ by representing a system in the form of \_\_\_\_\_\_
  - a) Time domain, first order differential equations
  - b) Frequency domain, first order differential equations
  - c) Time domain, second order differential equations
  - d) frequency domain, second order differential equations
- 8. The angle and magnitude condition for a stable system in root locus approach is
  - a)  $\angle G(s)H(s) = \pm (2q-1)180^{\circ}$  and |G(s)H(s)| = -1
  - b)  $\angle G(s)H(s) = \pm (q+1)180^{0}$  and |G(s)H(s)| = 1
  - c)  $\angle G(s)H(s) = \pm (2q+1)180^{\circ}$  and |G(s)H(s)| = 1
  - d)  $\angle G(s)H(s) = \pm (q+1)180^{\circ}$  and |G(s)H(s)| = -1

9. The root locus plot starts from \_\_\_\_\_ nd ends at \_\_\_\_\_

- a) Open loop zero, open loop pole
- b) Infinity , open loop pole
- c) Open loop pole, open loop zero or infinity
- d) Infinity, open loop zero
- 10. The number of branches of root locus plot for  $G(s)H(s)=K/(s+2)^3$ 
  - a) 1 b) 2 c) 3 d) 4
- 11. The Nyquist plot for G(s)H(s)=10/s(s+1)(s+\_2) will cross the real axis axis at
  - a) 8+j0
  - b) -0.8+j0
  - c) 0.8+j0
  - d) 0+j8

12. The velocity error constant for G(s)H(s)=10(1+s)/s(1+2s) will be

- a) 1 b) 10 c)5 d) 0
- 13. The velocity error constant for G(s)H(s)=10(1+s)/s(1+2s) will be

a)1 b) 10 c)5 d) 0

14. The steady state response of a system is that part of time response that goes to

\_\_\_\_\_ as time goes to \_\_\_\_\_\_

- b) Infinity, infinity
- c) Zero, infinity
- d) Zero, zero

a) Infinity, zero

- 15. The laplace transform of unit ramp function is
  - a) 1 b) 1/s c) 1/s<sup>2</sup> d) 1/s<sup>3</sup>
- 16. In order to find stability from routh Hurwitz criteria, the number of \_\_\_\_\_\_ in the first column of array, indicates \_\_\_\_\_\_
  - a) Zeros, no. of roots with positive real part
  - b) ones, no. of roots with positive real part
  - c) sign changes, no. of roots with positive real part
  - d) sign changes, no. of roots with negative real part
- 17. The range of K for for stability for characteristic equation  $s^3+2ks^2+(k+2)s+4=0$  is
  - a) K=1
  - b) K>2.73
  - c) K<2.73
  - d) K>10

18. Using the property of state transition matrix  $\phi^{-1}(t) =$  \_\_\_\_\_

- a)  $\emptyset^{-1}(-t)$
- b)  $\emptyset^{-1}(0)$
- c)  $\phi^{-1}(t)$
- d) I
- 19. According to Kalman's test, a linear time invariant continuos system described by state equations

 $[\dot{X}] = [A][X] + [B][U]$ 

[Y]=[C][X]

Is completely controllable if the rank of \_\_\_\_\_\_ matrix is equal to n

- a) [B : AB : AB<sup>2</sup>: .... : AB<sup>n-1</sup>]
- b) [A : AB :AB<sup>2</sup>: .... :AB<sup>n-1</sup>]
- c) [B : AB :A<sup>2</sup>B: .... :A<sup>n-1</sup>B]
- d) [B : AB : A<sup>2</sup>B: .... : A<sup>n-1</sup>B]
- 20. Gain margin is the reciprocal of magnitude |G(jw)| at the frequency at which
  - a) Phase angle is -180
  - b) Phase angle is -120
  - c) Phase angle is 0
  - d) Phase angle has no relation.
- 21. The gain crossover frequency is one where the magnitude of open transfer function is
  - a) 10 db
  - b) 1db
  - c) 0 db
  - d) -1db
- 22. When a pole is added in the forward path of a second order system
  - a) Band width decrease
  - b) Rise time reduces

- c) Resonant peak reduces
- d) System becomes more stable
- 23. Which of the following is not time response specification
  - a) Maximum overshoot
  - b) Delay time
  - c) Rise time
  - d) Band width
- 24. If initial slope of Bode plot is +20 b/d, it indicates presence of
  - a) Zero at origin
  - b) Pole at origin
  - c) Zero at infinity
  - d) Pole at infinity
- 25. The check for , a part of real axis lies on root locus , is
  - a) If number of poles to the right of section is odd
  - b) If number of zeros to the right of section is odd
  - c) If number of poles plus zeroes to the right of section is even.
  - d) If number of poles plus zeroes to the right of section is odd